


Calculate the kinetic energy of rotation of a circular disc of mass 1 kg

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If we push on an object in the direction forward, while the object is going forward, we make positive work on the object. The object accelerates, because we are pushing it on it. F = but. Earn kinetic energy. The translational kinetic energy of an object with mass M, whose center center moves with speed V is $K = \frac{1}{2}mv^2$. Translation kinetic energy = $\frac{1}{2} \text{ mass} \cdot \text{Speed}^2$ kinetic energy increases quadratically with speed. When the speed of a machine doubles, its energy increases a four factor. A rotating object has a kinetic energy, even when the object as a whole has no translational movement. If we consider the object consisting of a collection of particles, so every particle I kinetic energy $k_i = \frac{1}{2}mv_i^2$. The total kinetic energy of the rotating object is therefore given by $K = \sum k_i = \sum \frac{1}{2}mv_i^2 = \frac{1}{2} \sum v_i^2 = \frac{1}{2} \sum r_i^2 \omega^2 = \frac{1}{2} \omega^2 \sum r_i^2 m_i$. WRITE $K = \frac{1}{2} \omega^2 \sum r_i^2 m_i = \frac{1}{2} \omega^2 I$. The quantity in parenthesis is called the moment of inertia, $I = \sum r_i^2 m_i$ of the object on the rotation axis. The moment of inertia of a system on an axis of rotation can be found by multiplying the mass of every particle in the system from the square of its distance perpendicular R_i by the rotation axis and summarizing all these products, $I = \sum m_i r_i^2$. For A system with a mass distribution continues the sum turns into an integral, $I = \int r^2 dm$. The Unity of the moment of the inertia are mass units of square distance, for example KGM². When an object is rotating on an axis, its rotational kinetic energy is $K = \frac{1}{2}I\omega^2$. rotational kinetic energy = $\frac{1}{2}$ moment of inertia * (angular speed)². When the angular speed of a swivel wheel Double, its kinetic energy increases by a factor of four: When an object has the translator and the rotary movement, we can look at the movement of the mass center and the movement of the center of mass separately. The total kinetic energy is the sum of the translational kinetic energy of the center of mass (cm) and rotational kinetic energy on the cm. The moment of inertia of an object depends on the mass of the object, and on how this mass is distributed with respect to the rotation axis. The moment of the inertia is always defined with respect to a rotation axis. Far far most of the mass comes from the axis of rotation, the greater the rotational inertia (moment of inertia) of the object. Example: Imagine two wheels with the same mass. One is a solid wheel with its mass evenly distributed throughout the structure, while the other has most of the mass concentrated near the edge. The wheel with the mass near the edge has the largest moment of inertia. Example: The moment of inertia of a circular disk that turns around an axis through its perpendicular center to the plane of the disk differs from the moment of a disk that runs on an axis through its center in the from the disc. Moments of inertia of many objects with symmetrical mass distribution of about different axes of symmetry symmetry Be looked at the tables. Link: [a](#), list of moments of inertia problem: three particles are connected by rigid rods of negligible mass that are located along the Y axis as shown. If the system rotates around the X axis with a corner speed of 2 rad / s, find (a) I , the moment of inertia around the XE axis the kinetic energy of total rotation rated by $\frac{1}{2} I \omega^2$, and (b) v , the linear speed of each particle and the total kinetic energy evaluated by $\sum \frac{1}{2} m_i v_i^2$. Solution: Reasoning: the moment of inertia is $I = \sum m_i r_i^2$. here r_i is the perpendicular distance of the particle i from the X axis. The linear speed of the particle i is $v_i = \omega r_i$. Details of the calculation: (a) $I = (4 \text{ kg})(9 \text{ m}^2) + (2 \text{ kg})(4 \text{ m}^2) + (3 \text{ kg})(16 \text{ m}^2) = 92 \text{ kgm}^2$. $\frac{1}{2} I \omega^2 = \frac{1}{2} (92 \text{ kgm}^2) (4 \text{ rad/s})^2 = 736 \text{ J}$. rotation kinetic energy is $k = \frac{1}{2} I \omega^2 = \frac{1}{2} (4 \text{ kg})(9 \text{ m}^2) + (2 \text{ kg})(4 \text{ m}^2) + (3 \text{ kg})(16 \text{ m}^2) = 92 \text{ kgm}^2$. $\frac{1}{2} I \omega^2 = \frac{1}{2} (92 \text{ kgm}^2) (4 \text{ rad/s})^2 = 736 \text{ J}$. (b) The linear speed of the mass of 4 kg is $v = \omega r = 4 \text{ rad/s} \cdot 3 \text{ m} = 12 \text{ m/s}$. / if its kinetic energy is the linear speed of the Mass of 2 kg is $v = 4 \text{ m/s}$ / if its kinetic energy $\frac{1}{2} m v^2 = 16 \text{ J}$ / a linear speed of the mass of 3 kg $\frac{1}{2} m v^2 = 8 \text{ m}$ / if its kinetic energy is $\frac{1}{2} I \omega^2 = 96 \text{ J}$ / a sum of the kinetic energies of the three particles $\frac{1}{2} I \omega^2 = 184 \text{ J}$. Problem: The four particles in the figure on the right are connected by rigid rods. The origin is at the center of the rectangle. I , ω , calculate the moment of inertia of the system around Z axis. Solution: Reasoning: The inertia moment is $I = \sum m_i r_i^2$. Calculation details: each particle is a distance $r = (9 + 4) \text{ m} = 13 \text{ m}$ from the rotation axis. $I = (3 \text{ kg} + 2 \text{ kg} + 4 \text{ kg} + 2 \text{ kg}) (13 \text{ m})^2 = 143 \text{ kgm}^2$. Problem: Find the moment of inertia of a very thin circle of mass M and radius R around its axis of symmetry. Solution: Motivation: the mass is distributed continuously, then $I = \int r^2 dm$. $I = \int_0^R r^2 dm$. $I = \int_0^R r^2 \rho \pi r dr = \frac{1}{4} \pi \rho R^4$. all the DM mass elements are a distance perpendicular R from the Rotation axis. $I = \int_0^R r^2 dm = \int_0^R r^2 \rho \pi r dr = \frac{1}{4} \pi \rho R^4$. Parallel axis theorem Consider a composite object, like the two discs joined in the figure on the right, whose center center is at the origin. To find the moment of inertia of the object Compared to CM you can use the parallel axis theorem. This theorem claims that the inertia moment of an object compared to any axis is equal to the sum of two terms. FIRST TERM It is the product of the mass of the M object multiplied by the distance square of its center center from the axis in question. $I = I_{CM} + MR^2$. We can treat the composite object as the sum of its parts, and for each part calculating the moment of inertia around the Z axis. For disk 1 we have $I_1 = I_{CM1} + M_1 R_1^2$, and for disk 2 we have $I_2 = I_{CM2} + M_2 R_2^2$. The moment of the inertia of the composite object around the Z axis is therefore $I = I_1 + I_2$. For a uniform disk of the mass M is the moment of inertia about an axis through the relative center and perpendicular to the plane of the disk is $I = \frac{1}{2} MR^2$. For the object in the figure we have the time of the axis $(\frac{3}{2} MR^2 + \frac{3}{2} MR^2) = 3MR^2$. Rolling the kinetic energy of an object with translational and rotational movement is the sum of its translation and its rotational kinetic energy. Translation kinetic energy = $\frac{1}{2} m v_{cm}^2$. Rotational kinetic energy = $\frac{1}{2} I \omega^2$. Total Kinetic Energy = $\frac{1}{2} m v_{cm}^2 + \frac{1}{2} I \omega^2$. Consider a wheel of the radius R and mass m rolling on a flat surface in the X-Y plane. The shift Δx and angular shift $\Delta \theta$ are related through $\Delta x = R \Delta \theta$. The magnitudes of the linear speed and the angular speed are related through $v_{cm} = R \omega$. The kinetic energy energy is the sum of the kinetic energy of the movement of the center of mass, $\frac{1}{2} m v_{cm}^2$, and the kinetic energy of the movement of the center of mass, $\frac{1}{2} I \omega^2$. The total kinetic energy is $K_{tot} = \frac{1}{2} m v_{cm}^2 + \frac{1}{2} I \omega^2 = \frac{1}{2} m v_{cm}^2 + \frac{1}{2} I \left(\frac{v_{cm}}{R}\right)^2 = \frac{1}{2} m v_{cm}^2 \left(1 + \frac{I}{mR^2}\right)$. Example: Assume the wheel is a uniform disk. The moment of inertia I of a uniform disc on an axis perpendicular to the plane of the disc through its cm is $\frac{1}{2} m R^2$. The kinetic energy of the disc is therefore $K_{tot} = \frac{3}{4} m v_{cm}^2$. The relationship between rotational kinetic energy translation is $E_{trans} / E_{rot} = MR^2 / I$. If two rolling objects have the same total kinetic energy, the object with the smallest moment of inertia has the kinetic energy of the broader translation and the greater speed. Problem: hiring a disc and a ring with the same radius rolls up a slope of height h and that angle. If both start from rest at $T = 0$, which will reach the fund first? Solution: reason for you and then look at this video clip. Your answer has been corrected? Module 8: Question 2 Suppose you are planning a racing bicycle and the time comes to work on the wheels. You are told that the wheels must be of a certain mass, but you could design them as wheels with rays (like the traditional wheel bike) or you can make them as having solid circles to the end. What design would you choose as the aspect of the machine races is the most important? ω , please, explains! Discuss this with your study companions in the discussion forum! Module 8: Question 3 Describe the energy transformations involved when a yo-yo is launched down and then salt returns its string to be captured in the user's hand. Discuss this with your study companions in the discussion forum! Rotational or angular energy kinetic energy is the kinetic energy due to the rotation of an object and it is part of its total kinetic energy. Looking at rotational energy separately around the axis of a rotation object, we observe the following dependence on the moment of inertia: and rotational = $\frac{1}{2} I \omega^2$. Where I is the moment of inertia around the rotation axis $E_{rot} = \frac{1}{2} I \omega^2$ is kinetic energy mechanical workFor or applied during rotation is the Times torque The rotation angle. The instantaneous power of angular acceleration body is the couple times the angle speed. For floating objects (not thirstry), the rotation axis is commonly around its mass center. Note the close relationship between the result for rotational energy and the energy held by linear (or translational) movement: and Traslational = $\frac{1}{2} m v^2$. (MALAMSTYLY (TRANSLATIONAL)) = $\left\{ \frac{1}{2} m v^2 \right\}$ in the rotating system, the moment of inertia, I, takes the role of mass, m and angle speed, ω , takes the role of linear speed, v. The rotational energy of a rolling cylinder varies from half of the translational energy (if it is massive) to the same as the translation age (if it is empty). One example is the calculation of rotational kinetic energy of the Earth. Since the Earth has a period of about 23.93 hours, it has an angular speed of $7.29 \cdot 10^{-5} \text{ rad/s}$. The Earth has a moment of inertia, $I = 8.04 \cdot 10^{37} \text{ kg} \cdot \text{m}^2$. [1] Therefore, it has a rotational kinetic energy of $2.138 \cdot 10^{29} \text{ J}$. A good example of actually using Earth's rotational energy is the location of the European space space in French Guiana. This is in about 5 degrees of the equator, so rocket launches (for mainly geo-stationary satellites) from here to the east get almost all full rotation speed of the Earth to the equator (about 1,000 mph, a sort of "Sling-shot" benefit). This saves significant rocket fuel for launch compared to the rocket launched by Easterly by the Kennedy Space Center (USA), which only get about 900 mph added benefit due to the low relative rotation speed of the Earth to the north latitude of 28 degrees. Part of Earth's rotational energy can also be exploited using tidal power. An additional friction of the two global tidal waves creates energy in a physical way, infinitely slowing the Earth's angular speed ω . Due to the preservation of the angular momentum, this process transfers the angular momentum to the orbital movement of the moon, increasing its distance from Earth and its orbital period (cf. Tide Block for a more detailed explanation of this process). See also the flywheel List of energy storage projects Rotor rotor projects Rotational spectroscopy References [^] Inertia Moment - Earth, Wolfram recovered from " [HTTPS://en.wikidex.org/w/](https://en.wikidex.org/w/)

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